

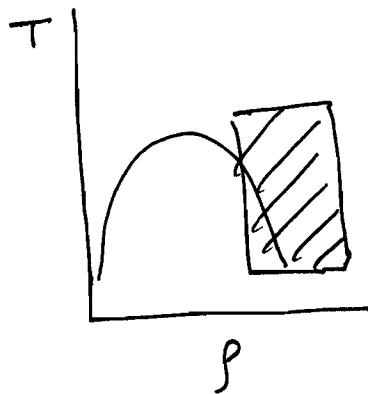
## Flat Histogram Methods

- Goal: obtain free energies to high accuracy
- Direct determination of thermodynamic potentials

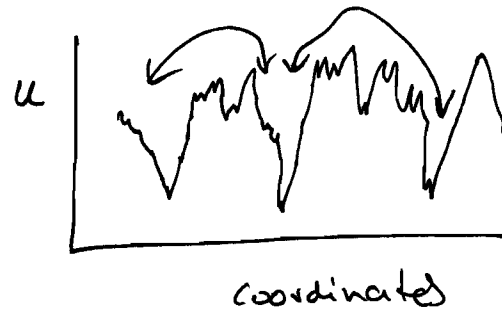
$$S = k \ln \Omega$$

$$A = -kT \ln \Omega$$

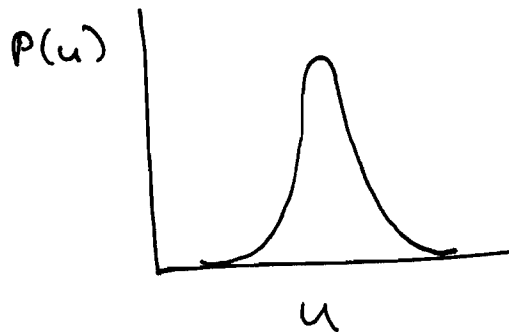
- Broad Sampling of configurations



effective sampling overcomes barriers



Canonical  
Simulations  
(NVT)



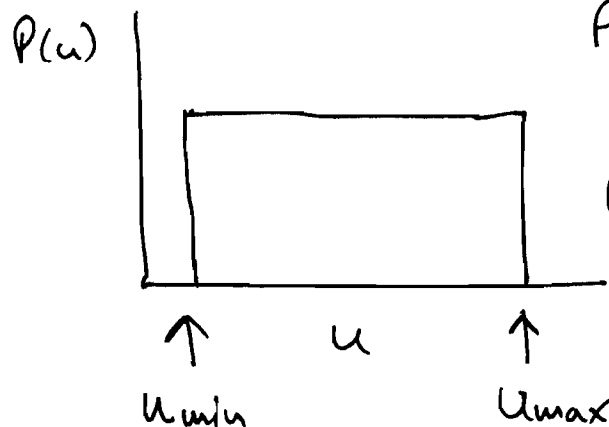
$$P(\vec{r}^N) \propto e^{-u/kT}$$

$$P(u) \propto \underline{\Omega}(u) e^{-u/kT}$$

Flat  
Histograms

no temperature

Defined  $u_{\min}$ ,  
 $u_{\max}$



$$P(\vec{r}^N) \propto \frac{1}{\underline{\Omega}(u)} = e^{-S(u)}$$

$$P(u) \propto \frac{\underline{\Omega}(u)}{\underline{\Omega}(u)} = \text{const.}$$

But...  $\rho(u)$  is unknown!

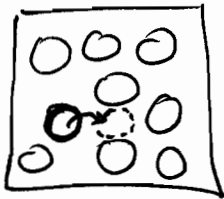
→ Accumulate probabilities of visiting microstates  
 [F. Wang-Landau *OP*, PRL B6:2050 (2001)]

Also: Van, Fuller, de Pablo JCP 116:8745 (2002)

Shell, Debenedetti, A&P PRF 66:056703 (2002)

Initialize: assume  $S=0$  for all states

$g=1$  ("modification factor")



displacement move  $\Delta \vec{r}$  uniform  
 up to  $|\Delta r_{\max}|$

Acceptance criterion? [Detailed Balance]

$P(\text{old}) \cdot \alpha(\text{old} \rightarrow \text{new}) \cdot \text{Accept}(\text{old} \rightarrow \text{new}) =$

$P(\text{new}) \cdot \alpha(\text{new} \rightarrow \text{old}) \cdot \text{Accept}(\text{new} \rightarrow \text{old}) \Rightarrow$

$$\frac{\text{Accept}(\text{old} \rightarrow \text{new})}{\text{Accept}(\text{new} \rightarrow \text{old})} = \frac{P_{\text{new}}}{P_{\text{old}}} = \frac{1/\rho(u_{\text{new}})}{1/\rho(u_{\text{old}})} = \frac{\rho(u_{\text{old}})}{\rho(u_{\text{new}})}$$

Metropolis:

$$\text{Accept}(\text{old} \rightarrow \text{new}) = \min \left\{ 1, \frac{\rho(u_{\text{old}})}{\rho(u_{\text{new}})} \right\}$$

Since initially  $S=0 \Rightarrow \rho=1$  for all states,  
 simulation will sample states of high  $u$   
 (high  $\rho$ ) more than states of low  $u$

keep track of (a) estimate of  $\rho(u)$  by

setting  $\ln \underline{\rho}(u_n) = \ln \underline{\rho}(u_{n-1}) + g$  // Changing estimate of  $\rho(u)$

(b) visited states  $P(u)$  vs  $u$

As sampling is increased:



If the  $P(u)$  vs  $u$  histogram is "sufficiently flat"

(e.g.  $f = \frac{\text{max frequency}}{\text{min frequency}} < 2$ ) then

→ set  $g \leftarrow g/2$

→ reset histogram  $P(u)$

Repeat until  $g$  becomes smaller than a specified tolerance,  $g_{\text{min}} (\approx 10^{-3} - 10^{-5})$

- \* Simulation does not satisfy detailed balance as  $\rho(u)$  estimate is changing!
- \* Simple to implement
- \* Criterion for flatness of histograms affects quality of convergence
- \* States between  $u_{\text{min}}$  and  $u_{\text{max}}$  quickly sampled

Disadvantage: Limiting statistical quality,  
Inefficient use of simulation information

### Transition Matrix

J.S. Wang, R.H. Swendsen

J. Stat. Phys. 106:245 (2001)

Probabilities of proposed moves between states:

$$\frac{P_{\text{propose}}(u_2 \rightarrow u_1)}{P_{\text{propose}}(u_1 \rightarrow u_2)} = \frac{\underline{\omega}(u_1)}{\underline{\omega}(u_2)}$$

	...	$u_{j-1}$	$u_j$	$u_{j+1}$
$u_{i-1}$				
$u_i$			$C_{ij}$	
$u_{i+1}$				
⋮				

$C_{ij}$ : transition matrix

Accumulate during run:

For any proposed move  $u_i \rightarrow u_j$

$$C(u_i, u_j) \leftarrow C(u_i, u_j) + 1$$

After many moves

$$P_{\text{propose}}(u_i \rightarrow u_j) \approx \frac{C(u_i, u_j)}{\sum_K C(u_i, u_K)}$$

Estimate of  $\Delta S = \frac{\underline{\omega}(u_2)}{\underline{\omega}(u_1)}$  from

$$P_{\text{acc}}(1 \rightarrow 2) = \exp(-\Delta S) = \frac{\underline{\omega}(u_1)}{\underline{\omega}(u_2)} = \frac{P_{\text{propose}}(2 \rightarrow 1)}{P_{\text{propose}}(1 \rightarrow 2)}$$

Algorithm: (1) Initialize Transition matrix to zeros for all states

Algorithm (cont.) (2) propose and accept/reject moves using the current value of

$$P_{acc} = \frac{P_{propose}(2 \rightarrow 1)}{P_{propose}(1 \rightarrow 2)}$$

- (3) Record proposed move in transition matrix
- (4) Stop when sufficient statistics have been gathered; generate  $\underline{Q}(u)$  from proposal probabilities

### Discussion / Comparisons w/ W-L

- \* States are not uniformly sampled, can take time to visit less likely (low  $\underline{Q}$ ) states
- \* Quality of results continues to improve

Combination: WL-TM: Shell et al., JCP 119:1406 (2003)

W-L propagation / quick sampling of states

TM estimation of  $\underline{Q}(u)$ : more accurate, continuous improvement